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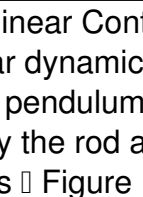
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length of the pendulum, $m > 0$ is the mass, $k > 0$ is a friction parameter and θ is the angle
subtended by the rod and the vertical axis through the pivot point, see Figure 1.1. PSfrag
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Exercises in Nonlinear Control Systems

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